Omron TM Collaborative Robots





Omron TM Collaborative Robots

Omron's lineup of collaborative robots includes a variety of models to guarantee the right reach and payload capacity for different applications, including mobile robot-compatible (DC) versions.







Designed to meet safety regulations ISO 10218-1 (including TS 15066) and ISO 13849-1.



















Key industries and applications

Omron TM Collaborative Robots are designed for a wide variety of applications in a number of industries.

Key Industries

Automotive



Food & Commodities



Digital & Semiconductor





Assembly:

Our cobots can improve throughput and consistency of repetitive or complex assembly tasks including part joining, insertion, tool changing, and working alongside people.

Mobile Manipulation:

Mounting an Omron TM cobot onto an Omron LD mobile robot automates not only materials transport, but also complicated picking operations.

Palletizing:

Our space-saving cobots can streamline end-of-line case stacking onto a pallet. With built-in vision, cases can be sorted by barcode or other visual indication.

Packaging:

Our cobots can inspect and sort products, before putting them into cases. Customers can quickly adapt production lines to new products or seasonal models.

Machine Tending:

A cobot can be used to tend CNC machines, injection molding machines, stamping and punch pressers, grinding, and cutting machines, relieving workers from repetitive and dangerous work.

Pick and Place with Inspection:

Our cobots feature a built-in vision system that allows for easy pick-and-place together with sophisticated inspection, without the need for installing additional cameras or lighting equipment.

Screwdriving:

Our cobots add precision and consistency to your screwdriving and parts fastening applications. A complete ready-to-use solution is provided with a screwdriving kit and pneumatic control box.

Easy to use

With graphical programming, hand guidance, and intelligent vision, Omron TM cobots are designed to be easy and intuitive. Customers can set up simple applications in just a few minutes.

Hand Guidance

Hand guidance mode allows users to easily set points and assign tasks to the robot. With buttons built into the cobot arm, users can guide the robot into position and automatically record the position in the software.



ISO/TS 15066 Oriented Safety Settings

Our unique patented "body region safety settings" have preset safety parameter values, based on TS 15066 and robot kinematics. There is no need to understand complicated safety calculations to set up a safe application.

Intelligent Vision

Our built-in vision system allows for quick setup of pick-and-place tasks, with the help of easy hand guiding and landmark positioning.

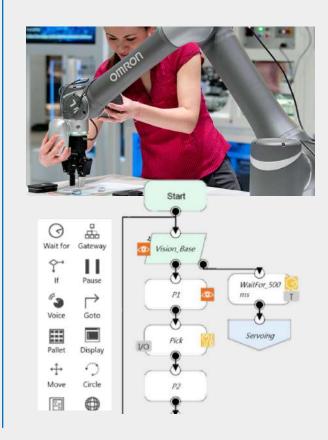


Landmark

A landmark is a physical object that can be recognized by the robot's built-in camera, and acts as a beacon to help the robot navigate. The robot uses a Landmark as a reference point so it can better locate objects within the workspace. During high-mix, low-volume production with quick changeovers, customers can redeploy the robot without spending time to recalibrate the vision system.

Graphical Programming

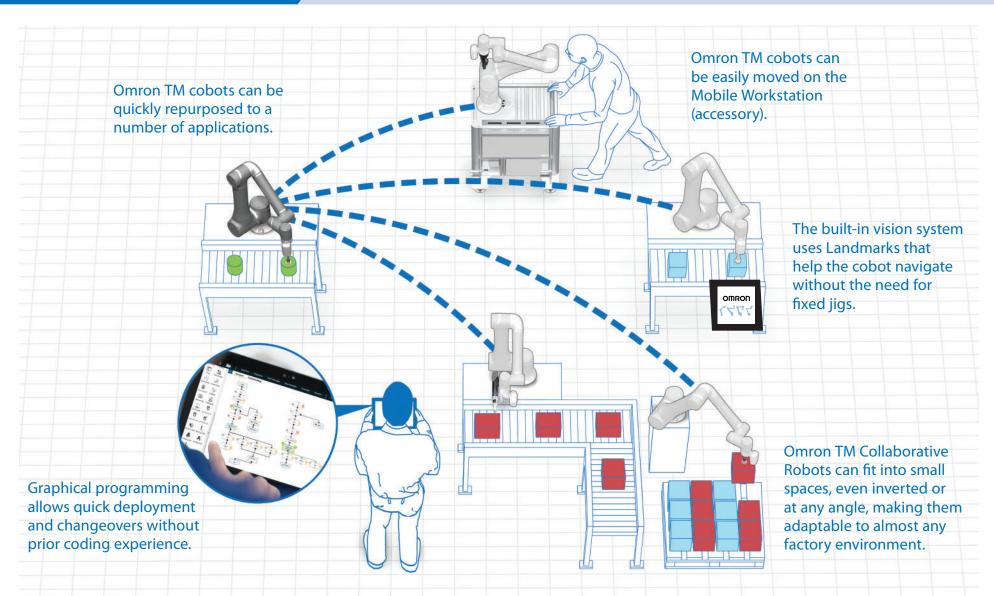
Intuitive programming allows users to automate a task with flow-based software, creating full workflows with a click-and-drag method.





Designed for flexible manufacturing

Omron TM Collaborative Robots are designed to be easily redeployed to different tasks and applications, making production as flexible as needed.



Built-In Vision

Users can set up vision tasks for immediate deployment without going through complex steps of integrating external cameras or lighting equipment. For even greater utility, users can choose to add up to two optional external cameras to best suit their unique application needs.



Standard Vision Package Pattern Matching Contrast Barcode Enhancement QR Code (Shape) Color Plane Pattern Matching Color Classifier Extraction (Image) [ABC] [DEF] Blob Finder String match Smoothing Thresholding Anchor Fiducial Mark Matching Flip **Optional Vision Package** Pose Variation Counting Gauge Line Burr (Shape) (Blobs) (Distance & Angle) 3.14¹ Pose Variation OCR Counting Circle Burr (Image) (Shape) (Number) Specific Color OCR Counting Area Size (Letter) (Image)

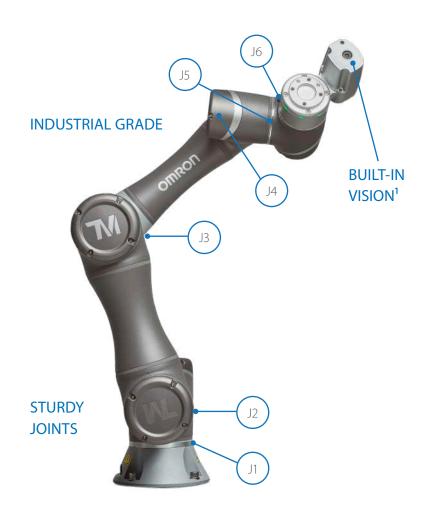
Counting

(Edges)

Reference Image



Anatomy of an Omron TM Cobot







- 1. VISION button teaches vision tasks and task sequences
- 2. POINT button records position in cobot program
- 3. FREE button allows hands-on teaching



- 4. Analog I/O port
- 5. Indicator light ring shows robot status
- 6. Digital I/O port



- 7. Built-in camera with integrated light
- 8. Gripper button
- 9. End-of-arm tooling flange

Plug & Play

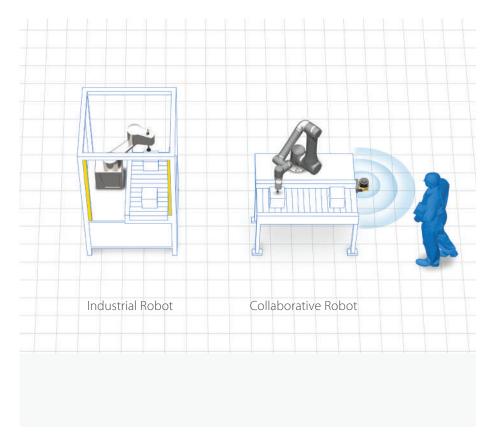
Omron has partnered with a select number of companies to offer a wide variety of peripherals that quickly and easily integrate with our cobots, allowing for a faster deployment and return on investment. They are collectively referred to as Plug & Play devices and software, designed to serve a broad range of customer applications and meet the highest testing standards of Omron.





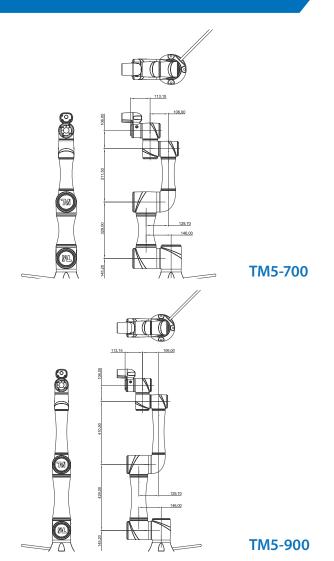
Choosing Cobots vs. Industrial Robot

Collaborative Robots have changed the way the traditional factory used to work. Designed to "collaborate" with people, cobots offer users a safe and easy to use feature set that can eliminate physical cages as well as the need for highly trained robot programmers.



Traditional	Industrial Robots	Omron Cobots		
Safety	Needs a physical barrier, such as a fence or cage, to ensure safety.	Designed to be inherently safe but may need safety sensors to ensure that the application is safe (e.g. Omron safety laser scanner) based on risk assessment. Typically does not need physical barrier if working in collaborative mode. Software safety setting is easy with graphical user interface.		
Workspace	Separated from human workspace.	Can be shared with people.		
Footprint	Large	Small		
Flexibility	No. Fixed to one location and works on dedicated task.	Yes. Can be moved between locations during the day to work on different tasks. Built-in camera and Landmark positioning enable quick relocation.		
Programming	Difficult. Requires skill and training.	Easy. Can be done with minimal training.		
Setup	Requires advanced skills and is time-consuming.	Quick and easy.		
Application	Fit for mass production at high speeds.	Fit for high-mix, low-volume production at a speed comparable to human workers. Can be used at high speeds with safety measures.		
Cycle Time (Pick & Place)	Down to seconds	Over 5 seconds		
Speed of Process (Path)	Below 8.2 m/s	Below 1.4 m/s		
Repeatability	+/- 0.02 mm	+/- 0.05 mm		
Environment	IP requirements above IP54	IP54 (robot arm), IP32 (control box)		
Process Complexity	Can be complex	Should be simple		

Technical Data TM5

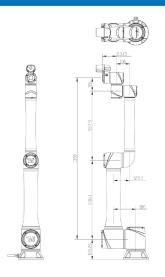


1. No-camera	version	available	on	request.

TM5 S	pecificatio	ns				
Model		TM5-700	TM5-900	TM5X-700	TM5X-900	
Weight 22		22.1kg	22.6kg	21.8kg	22.3kg	
Maximur	n Payload	6kg 4kg 6kg			4kg	
Reach		700mm	900mm	700mm	900mm	
Typical S	peed	1.1m/s	1.4m/s	1.1m/s	1.4m/s	
	J1,J6	+/- 270°	+/- 270°	+/- 360°	+/- 360°	
Joint ranges	J2,J4,J5	+/- 180°	+/- 180°	+/- 360°	+/- 360°	
runges	J3	+/- 155°				
Curred	J1~J3	180°/s 225°/s				
Speed	J4~J6					
Repeatal	oility	+/- 0.05 mm				
Degrees	of freedom	6 rotating joints				
		Digital in	Digital out	Analog in	Analog out	
I/O ports	Control Box	16	16	2	1	
ports	Tool	4	4	1	0	
I/O powe	r supply	24V 2.0A for control box a	and 24V 1.5A for tool			
IP classifi	cation	IP54 (Robot Arm); IP32 (Control Box)				
Power co	nsumption	Typical 220 watts				
Tempera	ture	The robot can work in a temperature range of 0-50°C				
Power su	pply	100-240 VAC, 50-60 Hz or 22-60 VDC				
I/O Interf	ace	3×COM, 1×HDMI, 3×LAN, 4×USB2.0, 2×USB3.0				
Commun	ication	RS232, Ethernet, Modbus TCP/RTU (master & slave), Optional EtherNet/IP or PROFINET				
Program Environn	•	TMflow, flowchart based				
Certificat	ion	CE, SEMI S2 (optional)				
Robot Vis	sion					
Eye in Ha	nd (Built in)	1.2M/5M pixels, color camera N/A				
Eye to Ha	nd (Optional)	Support Maximum 2 GigE cameras				

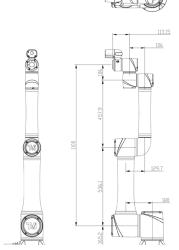


Technical Data TM12/14



TM12

TM14



1. No-camera version available on request.

TM12/14 S	Specificatio	ns			
Model		TM14	TM12	TM14X	TM12X
Weight		32.6Kg	33.3Kg	32.3Kg	33Kg
Maximum Payload		14kg	12kg	14kg	12kg
Reach		1100mm	1300mm	1100mm	1300mm
Typical Speed		1.1m/s	1.3m/s	1.1m/s	1.3m/s
	J1,J6	+/- 270°	+/- 270°	+/- 360°	+/- 360°
Joint ranges	J2,J4,J5	+/- 180°	+/- 180°	+/- 360°	+/- 360°
	J3	+/- 163°	+/- 166°	+/- 163°	+/- 166°
	J1~J2	120°/s			
	J3	180°/s			
Speed	J4~J5	150°/s	180°/s	150°/s	180°/s
	J6	180°/s			
Repeatability		+/- 0.1 mm			
Degrees of free	edom	6 rotating joints			
		Digital in	Digital out	Analog in	Analog out
I/O ports	Control Box	16	16	2	1
	Tool	4	4	1	0
I/O power supply		24V 2.0A for control box and 24V 1.5A for tool			
IP classification		IP54 (Robot Arm); IP32 (Control Box)			
Power consumption		Typical 220 watts			
Temperature The robot can work in a temperature range of 0-50°C					
Power supply		100-240 VAC, 50-60 Hz or 22-60 VDC			
I/O Interface		3×COM, 1×HDMI, 3×LAN, 4×USB2.0, 2×USB3.0			
Communicatio	n	RS232, Ethernet, Modbus TCP/RTU (master & slave), Optional EtherNet/IP or PROFINET			
Programming	Environment	TMflow, flowchart based			
Certification		CE, SEMI S2 (optional)			
Robot Vision					
Eye in Hand (B	uilt in)	1.2M/5M pixels, N/A color camera			
Eye to Hand (O	ptional)	Support Maximum	2 GigE cameras		



Global Network

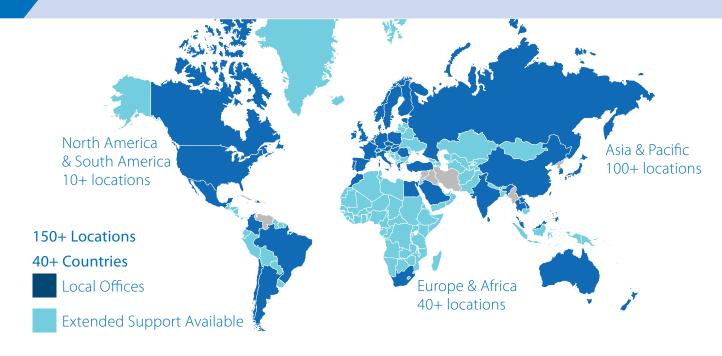
For decades, Omron's safety services have been the partner of choice of global brands and machine manufactures in automotive, food and beverage, consumer electronics and cosmetics industries. Our expertise in industrial, mobile, and collaborative robotics combined with 85+ years of experience in industrial automation gives us unparalleled expertise in safety.

Risk Assessment Service

Omron's Risk Assessment Service helps customers mitigate potential safety hazards before deploying a robotics solution. Our functional safety engineers bring unrivaled expertise to work with customers onsite, to identify relevant standards and requirements for human-machine interaction.

We offer:

- Support with process analysis, identification of application use cases, tasks, and potential collision points.
- Risk, compliance, and conformity assessment according to latest industry standards.
- Risk reduction strategies with a focus on shared human-robot workspace and end-effector design.



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